





## Table of contents

How to use this manual	21
Intended use	21
Safety instructions	22
EMC declaration	24
Information: Motorola I and Motorola II format	24
Operation overview	25
Checking the package contents	26
Technical specifications	26
Required tools and consumables	26
Safe and correct soldering	27
Performing a visual check	27
Mounting the locomotive decoder	28
Setting the locomotive decoder	31
Operation	32
FAQ	32
Manufacturer's note	33
Certification	34
Conditional warranty	34
Diagram: Setting the locomotive address	68
Circuit Diagram LD-G-1 (Fig. 1)	I
Circuit Diagram LD-W-1 (Fig. 2)	II
Connections 1: front LD-G-1 and LD-W-1 (Fig. 3a and 3b)	III
Connections 2: rear LD-G-1 (Fig. 4) and LD-W-1 (Fig. 5)	IV

(Pages I to IV in the centre of this handbook are removeable)

## How to use this manual

If you have no specialist technical training, this manual gives step-by-step instructions for safe and correct fitting of the module, and operation. Before you start, we advise you to read the whole manual, particularly the chapter on safety instructions and the FAQ chapter. You will then know where to take care and how to prevent mistakes which take a lot of effort to correct.

Keep this manual safely so that you can solve problems in the future. If you pass the kit on to another person, please pass on the manual with it.

## Intended use



### Caution:

Integrated circuits are very sensitive to static electricity. Do not touch components without first discharging yourself. Touching a radiator or other grounded metal part will discharge you.

The module can be used according to the specifications of this manual. It is designed for the mounting in a model railway locomotive with d.c. motor (LD-G-1) resp. a.c. motor (LD-W-1).

It evaluates the Motorola format data sent by the digital central unit to its address. The decoder controls the vehicle performance (velocity, direction of travel, acceleration), switches the lighting and four further optional functions.

The module is not suitable for children under the age of 14.

Reading, understanding and following the instructions in this manual are mandatory for the user.

Any other use of the kit is inappropriate and invalidates any guarantees.

## Safety instructions

### Mechanical hazards

Cut wires can have sharp ends and can cause serious injuries. Watch out for sharp edges when you pick up the PCB.

Visibly damaged parts can cause unpredictable danger. Do not use damaged parts: recycle and replace them with new ones.

### Electrical hazards

- Do not touch powered, live components.
- Do not touch conducting components which are live due to malfunction.
- Avoid short circuits.
- Do not connect the circuit to a higher voltage than designed.
- Impermissibly high humidity.
- Condensation building up can cause serious injury due to electrical shock.

Take the following precautions to prevent this danger:

- Never perform wiring on a powered module.
- Only use low power for this module as described in this manual and only use certified transformers.
- Connect transformers and soldering stations only in approved mains sockets installed by an authorised electrician.
- Observe cable diameter requirements.
- Assembling the kit should only be done in closed, clean, dry rooms. Beware of humidity.
- If the humidity in the room is too high, please do not start working until after a minimum of 2 hours of acclimatisation.
- Use only original spare parts if you have to repair the kit or the ready-built module.

## Fire risk

Touching flammable material with a hot soldering iron can cause life-threatening fire, burns and toxic smoke. Connect your soldering iron or soldering station only when actually needed. Use the correct soldering iron or station and never leave a hot soldering iron or station unattended.

## Thermal danger

A hot soldering iron or liquid solder accidentally touching your skin can cause skin burns. As a precaution:

- use a heat-resistant mat during soldering,
- always put the hot soldering iron in the soldering iron stand,
- point the soldering iron tip carefully when soldering, and
- remove liquid solder with a thick wet rag or wet sponge.

## Dangerous environments

A working area that is too small or cramped is unsuitable and can cause accidents, fires and injury. Prevent this by working in a clean, dry room with enough freedom of movement.

## Other dangers

Children can cause any of the accidents mentioned above because they are inattentive and not responsible enough. Children under the age of 14 should not be allowed to work with this kit or the ready-built module.

Little children can swallow small components with sharp edges. Life threatening! Do not allow components to reach small children.

In schools, training centres, clubs and workshops, assembly must be supervised by qualified personnel.

In industrial institutions, health and safety regulations applying to electronic work must be adhered to.

## EMC declaration

This product is developed in accordance with the European standards EN 55014 and EN 50082-1, tested corresponding to the EC - directive 89/336/EEG (EMVG of 09/11/1992, electromagnetic tolerance) and meets legal requirements.

To guarantee the electromagnetic tolerance you must take the following precautions:

- Connect the transformer only to an approved mains socket installed by an authorised electrician.
- Make no changes to the original parts and accurately follow the instructions, circuit diagram and PCB layout included with this manual.
- Use only original spare parts if you have to repair the kit or the ready-built module.

## Information: Motorola I and Motorola II format

The digital driving data is differently encoded and transmitted in the (old) Motorola I format and the (new) Motorola II format. The locomotive decoder is designed to evaluate data in Motorola II format. This limits its use in Motorola I format.

Since data of the auxiliary functions F1 to F4 sent in Motorola I Format cannot be evaluated by the locomotive decoder, it is not possible to switch these functions on or off when using Motorola I format.

Unlike the Motorola II format, no absolute direction data is sent in Motorola I format, but a single driving signal reverses the direction of travel. This has the following consequences:

1. If the change direction command is not recognized by the locomotive, it continues in the original direction.
2. If the decoder is switched off for some time and the direction data is not saved, the locomotive continues in its favourite direction when it is switched on again.

## Operation overview

The decoder is designed for operation in Motorola I or II format and can be adjusted to one of 255 addresses. It evaluates the digital data sent by the central unit to its address and transmits it to the locomotive.

### Function speed level and direction of motion

The speed level set at the central unit and the change-direction command are transmitted to the locomotive by the decoder. At a direction change the existing direction of travel is not saved, so the locomotive continues in Motorola I format in its preferred direction after the decoder has been off for some time.

### Acceleration and brake delay

Three variants of acceleration and brake delay are available: fast, medium and slow. By attaching solder bridges one of the three variants can be fixed.

### Function lighting

The lighting can be switched on and off according to the direction of travel from the central unit via the function "function". In addition, another optional accessory (e.g. cab lighting, noise module) can be switched on and off according to the direction of travel.

### Auxiliary functions in Motorola II format

The auxiliary functions **F1** to **F4** can be switched from the central unit. They are available to control optional accessories (e.g. smoke generator, cab lighting, noise module).

### Restrictions in Motorola I format

The auxiliary functions **F1** to **F4** are not available in Motorola I format. It is possible to control one accessory via the function "function" according to the direction of travel.



## Checking the package contents

Check the contents of the package for completeness:

- 1 module
- 1 manual

## Technical specifications

Data format	Motorola I and II
Supply voltage	12-22 Volt digital voltage
Current consumption (without connected loads)	ca. 10 mA
Max. current for motor	1.000 mA
Max. current per function output	500 mA
Max. total current	1.500 mA
Protected to	IP 00
Ambient temperature in use	0 - + 60° C
Ambient temperature in storage	-10 - + 80° C
Comparative humidity allowed	max. 85 %
Dimensions	ca. 25 x 17 x 8 mm
Weight	ca. 5 g

## Required tools and consumables

Make sure you have the following tools, equipment and materials ready for use:

- a heat-resistant mat
- a soldering iron stand with tip-cleaning sponge
- a small side cutter and wire stripper
- an electronic soldering iron (max. 30 Watt) with a fine tip
- tin solder (0,5 mm. diameter)
- wire (diameter:  $\geq 0,08 \text{ mm}^2$  for all connections)

## Safe and correct soldering



### Caution:

Incorrect soldering can cause fires (through excessive heat). Avoid this danger by reading the chapter **Safety instructions** again and following the directions given.

If you have had training in soldering you can skip this chapter.

- When soldering electronic circuits never use soldering-water or soldering grease. They contain acids that can corrode components and copper tracks.
- Only use tin solder SN 60 Pb (i.e. 60 % tin, 40 % lead) with rosin-based flux.
- Solder fast: long soldering can destroy components and copper tracks, and damages through plated holes.
- Use a small soldering iron with max. 30 Watt. Keep the soldering tip clean so the heat of the soldering iron is applied to the solder point effectively.
- Apply the soldering tip to the soldering spot in such a way that the part and the soldering spot are heated at the same time. Simultaneously add solder (not too much). As soon as the solder becomes liquid take it away. Hold the soldering tip at the spot for a few seconds so that the tin solder finds its way, then remove the soldering iron.
- Do not move the component for about 5 seconds after soldering. A glossy and perfect soldering spot should remain.
- To make a good soldering joint you must use a clean and unoxidised soldering tip. Clean the soldering tip with a damp piece of cloth, a damp sponge or a piece of silicon cloth.

## Performing a visual check

Damaged materials can cause injury. Parts damaged during transit can also be dangerous. Check the module for damage, missing parts or poor soldering. If you find damage, return the module for exchange.

## Mounting the locomotive decoder

Open the locomotive housing. Locate the position for the decoder. Disconnect the motor from the rail current collector respectively the change-over switch from the motor and rails if you have a locomotive with electronic change-over switch.

### **Caution:**

The interference suppression devices mounted to the motor or the connecting wire must not be removed! Motor and interference suppression devices are one unit. If even one part is removed, it can cause extreme interference!

### **Connecting the LD-G-1**

Follow the connections diagrams (fig. 4)! Solder the connections to the rails at points X1 and X2 (rear of the locomotive decoder) and the connections to the motor at the points X11 and X12 (rear of the locomotive decoder).

The connection to the rails is optional, but you must observe polarity when connecting the motor.

**Tip:** In three rail systems, connect the centre conductor to X2. The locomotive response to control data improves, compared with connection to X1.

### **Connecting the LD-W-1**

Follow the connections diagrams (fig. 5)! Solder the connections to the rails at points X1 and X2 (rear of the locomotive decoder) and the connections to the motor at the points X11, X12 and X19 (rear of the locomotive decoder).

### **Caution:**

The connections to the rails and motor must be made as shown in the diagram "connections"! Otherwise the locomotive decoder will not respond to the control data sent by the central unit.

## Connecting the lighting and other accessories

Follow the connections diagrams (fig. 3a and 3b)!

Disconnect any existing diodes in the leads to the lamps. Connect the lamps for forward motion to X4 and the lamps for reverse to point X5 (front of the locomotive decoder). If the lamps are already connected with one side to locomotive ground, you must solder in a diode between the decoder and the lamp (see fig. 3a) or you must connect the second side of the lamps according to fig. 3b to the return conductor (point X3 on the front of the decoder).

Connect other accessories (e.g. smoke generator, cab lighting), which are switched by the functions F1 to F4, to the points X7 to X10 (front of the decoder). You can connect the second side of the accessories either to the return conductor (point X3) or to locomotive ground. If connecting the accessory to locomotive ground you must solder in a diode.

### **Caution:**

The return conductor for all functions (point X3) must under no circumstances be connected to locomotive ground. Possible short circuit! The locomotive decoder will be damaged in operation.

**Tip:** If the second side of the lamps is connected to locomotive ground the lamps often flicker in operation. You can avoid the flickering of the lamps if you connect the second side to the return conductor (point X3) instead of locomotive ground.

### **Caution:**

If you connect the loads to the return conductor for all functions (point X3), the load must be insulated. The loads must not make contact with metal parts of the locomotive. Possible short circuit! The locomotive decoder will be damaged in operation.

## Connecting the LEDs

The function outputs of the locomotive decoder switch against decoder ground. For that reason you must connect the cathode (-) of the LED to the output of the relevant function.



### Caution:

If you use light-emitting diodes (LEDs) you must always operate them via a series resistor.

LEDs are available in many different models. There are LEDs with 2-5 mA, but also LEDs with 15-30 mA power consumption. The series resistor limits the current flow of the LED and will need to be calculated for each model. Ask for the max current rating when buying your LEDs.

You can connect several LEDs in parallel to each output. In this case every LED must have a series resistor of its own. If you connect several LEDs to one output in series, only one series resistor is needed. The number of LEDs connected in series to one output depends on the digital voltage.

You can determine the number of the LEDs that can be connected in series to one output from the following formula:

$$(\text{number of LEDs} + 2) \times 1,5 < \text{digital voltage}$$

### Fixing the locomotive decoder

After completing all connections fix the locomotive decoder with double-sided adhesive tape, for example.

### Using an NEM 652 interface connector

Contact	Connection	Colour of cable	Connecting points
1	Motor connection 1	orange	X11
2	Lighting back (-)	yellow	X5
3	Not used or F1	green	X7
4	Power supply left	black	X1
5	Motor connection 2	grey	X12
6	Lighting front (-)	white	X4
7	Common conductor for all functions (+)	blue	X3
8	Power supply right	red	X2


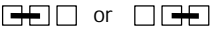

Some locomotives already have an NEM 652 interface connector mounted. Using a convenient connecting plug you save disconnecting the connections and you do not need to solder at the locomotive.

The list shows how to connect the contacts of the interface connector to the connecting points of the locomotive decoder.

## Setting the locomotive decoder

### Setting the acceleration and brake delay

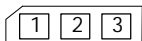
The locomotive decoder can be set to one of three different delays: fast, medium or slow. The setting is made by mounting solder bridges to X17 (on the front of the decoder, beneath the IC U1). The assignment is as follows:

Fast delay	No solder bridge	
Medium delay	Solder bridge between two optional solder pads	
Slow delay	Solder bridge across all the solder pads	

### Setting the locomotive address

The locomotive decoder can be set to one of 255 addresses. The setting is made by mounting solder bridges to X13 - X17 (on the front of the decoder, left of the IC U1) resp. X18 on the front of the decoder, right of the IC U1). The assignment is shown in the list on page 68.

The solder pads are numbered from the left side of the PCB as follows:



The solder pad "4" is identical with connecting point X18. If for one address two connections to solder pad 4 are given, two connections to point X18 must be made.

**Caution:**

Use a soldering iron with a small tapered point and max. 30 Watt to make the solder bridges. Take special care to avoid short circuits. If necessary, check the solder bridges with a magnifying glass to make sure that the solder bridges are closed correctly and solder has not short-circuited adjacent components or connections.

## Operation

### Emergency stop during active acceleration and brake delay

An emergency stop during acceleration and brake delay can be performed from the central unit by changing the direction of travel.

### Improvement of the driving characteristics

Locomotives with especially high current consumption or track sections with bad contacts (e.g. some types of points) may give an unsatisfactory performance after the mounting of the locomotive decoder. You can improve the locomotive performance by soldering a capacitor 220  $\mu\text{F}$  /  $\geq 25 \text{ V}$  in parallel to the capacitor C2 (rear of the locomotive decoder, see fig. 4 or 5).

The settings cannot be saved by the decoder and are lost after a power supply interruption of a certain length. When the interruption is only short, the capacitor C1 maintains the voltage and the settings are kept. You can lengthen this period of time by soldering a capacitor 47  $\mu\text{F}$  /  $\geq 6,3 \text{ V}$  in parallel to the capacitor C1 (rear of the locomotive decoder, see fig. 4 or 5).

## FAQ

- Parts are getting too hot and/or start to smoke.

**Disconnect the system from the mains immediately!**

Possible cause: one or more connections are soldered incorrectly.

→ Check the connections.

Possible cause: The connection of the motor is connected to locomotive ground.

→ Disconnect the connection from locomotive ground.

- The locomotive lighting does not correspond to its direction of travel.

Possible cause: The forward and backward light connections have been exchanged.

→ Check the connections.

Possible cause: The connections of the motor to the points X11 and X12 have been exchanged.

→ Exchange the connections.

- A lamp flickers (this is not a defect).

Possible cause: The lamp is connected with one side to locomotive ground.

→ If you do not want the lamp to flicker, disconnect it from locomotive ground, insulate it and connect it to the return conductor (point X3).

- The locomotive does not run.

Possible cause: The locomotive address is not set correctly.

→ Check the solder bridges (if necessary with a magnifying glass).

Possible cause (locomotive with LD-W-1): The connections to the rails (points X1 and X2) have been exchanged.

→ Exchange the connections.

If you cannot find the problem, please return the decoder for repair (address on the cover page).

## Manufacturer's note

According to DIN VDE 0869, the person who builds this kit or brings the circuit into operation is the manufacturer of the product. If he sells the product to another person he is responsible for passing on all the relevant papers. Domestic appliances assembled from a kit are deemed industrial products and must comply with health and safety regulations.



## Certification

This product conforms with the EC- directive 89/336/EWG on electromagnetic radiation and is therefore CE certified.

## Conditional warranty

This product is guaranteed for two years. The warranty includes free repair if the problem is due to material failure or incorrect assembly of the module by us. We guarantee the quality of the components.

Other claims are excluded. By law, we are not responsible for damages or secondary damages in connection with this product. We retain the right to repair, make improvements, supply spare parts or return the purchase price.

The following invalidate the warranty:

- using an unsuitable soldering iron, solder containing liquid acids or similar,
- if damage is caused by not following the instructions in this manual or the circuit diagram,
- if the circuit has been altered and repair attempts have failed,
- if arbitrary changes in the circuit are made,
- if parts are stored incorrectly and if the wires to the switches, the power resistors, etc. are made incorrectly,
- if the copper tracks or soldering points are damaged,
- if parts are placed incorrectly or the circuit is connected incorrectly,
- if damage occurs due to an overload of the circuit,
- if the wrong power or current is connected,
- if damaged by other persons,
- if damaged by the wrong use or abuse of the circuit,
- if parts are damaged due to static because they were touched before a discharge is performed.